

SCHOOL OF ENGINEERING  
& APPLIED SCIENCE  
**Department of Engineering  
Technology**

CONCURRENT  
PRESENTATIONS

**Friday, April 22  
9:30am-5pm**

**FREE & OPEN TO THE PUBLIC.**



# SENIOR DESIGN 2011 projects



## CONCURRENT MORNING PRESENTATIONS

### **Miami University Regionals**

Hamilton Campus  
Harry T. Wilks Conference Center

**9:30am**

#### **Mobile Access Ramp Development Specializing in Pontoon Boat**

**Bradley Rogers, Randy Zeiser**

Student engineers designed and built a prototype of a mobile equal access ramp to facilitate the safe and convenient transport of handicapped individuals in wheelchairs on and off a standard pontoon boats.

**10am**

#### **HVAC Trainer Thermodynamics & Heat Transfer Labs**

**Anthony Dahlinghaus,  
Jason Morningstar, Scott Harper**

Student engineers utilized an existing HVAC trainer to develop educational laboratories for Miami University Engineering Technology courses. Labs include specific heat, log mean temperature difference, and coefficient of performance equations that provide comparisons of measured and theoretical values.

**10:30am**

#### **Wireless Medical Motion Detection System**

**Michael Dando, Eric Seeborn,  
David Ryan**

Students designed a wireless device for tracking the movement of elderly or special needs patients that are prone to falls and injuries. The wireless device is small, portable and suitable for carrying in a pocket or attached to a dress.

**11am**

#### **Engineering Concepts & Components – Instrumentation Labs**

**Andrew George, Ben Risner,  
Brad Sanders**

Students constructed lab demonstrations to portray basic engineering concepts related to dynamics and strength of materials. These

lab demonstrations implemented various types of lab equipment along with interactive computer software used for system analysis and data collection.

**11:30am**

#### **Modular Oxygen Sensor & Application Analysis**

**Andy Bowden and Justin Clark**

Students designed and demonstrated the capabilities of a modular oxygen sensor manufactured by Marathon Monitors Inc. Students heated the sensor to 17500F, simulated an in-situ atmosphere, and described applications which require oxygen sensors.

### **North Central State College**

Kehoe Center, Shelby, OH

**9:30am**

#### **Web-Monitored Prony Brake Torque Transducer**

**Ross Lee, Brent Fogg**

This project had several objectives: measure the torque created by a capacitor start AC electric motor utilizing a Prony brake; store and analyze the collected data with Labview software; and share that information using a client/server network. This project will be used in EMET courses at Miami.

**10am**

#### **Automated Guided Vehicle (AGV) Using Webcam Based Vision**

**Aaron Siferd, Jonathon Cron**

Students implemented artificial intelligence to control an Automated Guided Vehicle (AGV). An RC car will be controlled to navigate a target using a webcam based vision system.

**10:30am**

#### **Automated Indexing Table**

**Colton Krupp, Paul Molnar,  
Joshua Storrer**

The purpose of this project was to design and develop an automatic material storage

### **What is Senior Design?**

Student teams conduct major open-ended research and design projects. Elements of the design process including establishment of objectives, synthesis, analysis, and evaluation are integral parts of the capstone. Real-world constraints such as economical and societal factors, marketability, ergonomics, safety, aesthetics, and ethics are also integral parts of the capstone.

and handling system for multi-robotic assembly operations. The system consists of a servo motor driven rotary indexing table which is fully controlled by a PLC microcontroller unit that can integrate with an industrial automation system infrastructure.

**11am**

#### **Improvement of Rolling Mill Process at Tosoh SMD, Inc.**

**Drew Thomas, Ryan Volant,  
Mike Sestito**

The objective of this project was to improve the current rolling mill process at the Tosoh SMD, Inc. Improvements were made in the areas of automation of the system, efficiency, operating cost, man power, reduction of time to complete the process, and implementation of safety requirements for OSHA.

**11:30am**

#### **Robot/Bottling System for Zane State College**

**Karli Niswonger, Matt Jenkins,  
Andrew Keister**

Students proposed and designed a bottling-conveyor operation for Zane State College. Students designed the bottle fill apparatus, brackets for the conveyor, as well as programming the robot and conveyor through a PLC.

CONCURRENT AFTERNOON PRESENTATIONS



WEBCAM AUTOMATED GUIDED VEHICLE



**Miami University Regionals**  
Hamilton Campus  
Harry T. Wilks Conference Center

**1pm**  
**Smartphone-Based RFID Reader**  
**Lyndon Pearson, Eric Duritsch**

Students developed a hardware and software interface to interface an RFID reader to a cellular phone or a pocket-size computing platform in order to obtain information from objects in proximity. Miami University IT services is interested in this application for inventory control applications.

**1:30pm**  
**Automated Drool Cart — Lyondell Basell Industries**  
**Scott Weber, Dan Baber, Craig Caudill**

Student engineers designed and built an automated drool cart for the extrusion coating operations at LyondellBasell Industries R&D center located in Cincinnati Ohio. This project focuses on the automation of a manual dumping process of heavy waste pans from the production line.

**2pm**  
**2010 Basic Utility Vehicle Competition Team**  
**Justin Welling, Greg Robertson, Mitchell Jones**

Students designed, fabricate and built a Basic Utility Vehicle (BUV) to aid impoverished citizens in the African country of Ghana.

Their design conformed to performance specifications provided by IAT (Institute for Affordable Transportation).

**2:30pm**  
**Toyota Solara Automated Vehicle Control System**  
**Bryan Allen, Andrew Rapach, Ronald Sorrell**

Student engineers designed and built systems to enable a Toyota Solara to be operated remotely. This vehicle was donated to Miami University by Toyota Motor Engineering & Manufacturing for student projects.

**3pm**  
**Wireless Network of Programmable Logic Controllers for Three Phase Motor Control**  
**Brandon Anderson, Harold Dicks, Andrew Knipp**

Students developed a wireless network of Programmable Logic Controllers (PLCs) for monitoring and control of industrial processes. The wireless network is constructed through the low-level integration of wireless adapters of a selected communication protocol (WiFi, Bluetooth or ZigBee) and conventional PLC systems.

**3:30pm**  
**FIRST Robotics Competition**  
**Sean Grubb, Roscoe Jeffries, John Schroder**

Student mentored the FIRST Robotics Team 1038 at Lakota East High School. They had a technical support role in the design and build of a robot in (6) weeks that will participate in the FIRST® Robotics national competitions.



**North Central State College**  
Kehoe Center

**1pm**  
**Improve and Expand Functions of a Hydraulic Test Bench with NI Modules**  
**Tyler Rauh, Brandon Hoffman, Tyler Goecke**

Students revamped a hydraulic test bench used by Crown Lift Trucks to test various hydraulic components. By incorporating NI modules, this project will enable the general purpose setup for a test and make the test bench more expandable.

**1:30pm**  
**Improving the Control System Efficiency in an Electric Truck**  
**Richard Gast, Josh Reagan**

Students upgraded an electric truck by adding an auto power delivery system and a temperature monitoring system so that an on board generator can provide power on demand to the truck. This project is sponsored by North Central State College.

**2pm**  
**Wind Turbine Simulation Facility Design and Implementation**  
**Clifford Green**

Students designed a wind turbine simulation facility to test a rectifier which can optimize wind turbines operation and generate more power. An alternative energy mounting design was modeled and built to attach energy harnessing devices onto cell phone towers.

**2:30pm**  
**Strain Gage Measurements on a Cantilever Beam**  
**Jake Nicodemus, Joe Panico, Marcus Lott**

Students designed a cantilever beam with a strain gage mounted on it. This project will be used in EMET courses at Miami.

**3pm**  
**Position Control Servomotor**  
**Ethan Kirkman, Harold Marlatt, Billy Rich**

The objective of this group was to improve the ENT 418 Servo Position Control Lab experience for Miami University. The group demonstrated speed control and transfer function modeling for this project. To accomplish this, a servo motor with a tachometer, PWM driver, and an operating program was utilized.